

NETWORK

A *network* is a quadruple $N = (G, s, t, c)$ where $G = (V, A)$ is a simple digraph. Every ordered pair (u, v) of nodes is assigned a non-negative *capacity* $c(u, v) \geq 0$. For an ordered pair $(u, v) \notin A$, we put $c(u, v) = 0$. There are two special nodes: the *source* s and the *target* t . In what follows we will assume that each node lies on a directed path from the source to the target.

A **flow** in a network $N=(G, s, t, c)$ is a mapping $f : V \times V \rightarrow R$ satisfying the following three conditions:

1. $f(u, v) \leq c(u, v), \forall u, v \in V$
2. $f(u, v) = -f(v, u), \forall u, v \in V$
3. $\sum_{v \in V} f(u, v) = 0, \forall u \in V - \{s, t\}$

The quantity $f(u, v)$, which may be positive, zero, or negative, is called the **flow from node u to node v** .

The quantity $|f| = \sum_{u \in V} f(s, u)$ is called the **total flow** of N .

Notes to the definition of flow:

By Condition 2 above, we have $f(u, u) = 0$, that is, the flow from a node into itself is zero.

By Condition 3, the total flow from each node different from source and target is zero. Using Condition 2, this can be rewritten as

$$\sum_{u \in V} f(u, v) = 0, \forall v \in V - \{s, t\}, \text{ that is, the total flow into each node}$$

different from source and target is zero.

If no arcs exist between nodes u and v , there can be no flow between them as $c(u, v) = c(v, u) = 0$ and so $f(u, v) \leq 0$ and $f(v, u) \leq 0$. Condition 2 then yields $f(u, v) = f(v, u) = 0$.

Summation formalism

We will use the following short-cut symbol where X and Y are sets of nodes:

$$f(X, Y) = \sum_{x \in X} \sum_{y \in Y} f(x, y)$$

We may also leave out the brackets “{“, “}” denoting sets. For example, in the formula $f(s, V - s) = f(s, V)$, $V - s$ is a shortcut for $V - \{s\}$.

Lemma 1

Let $N=(G, s, t, c)$ be a network where $G=(V, A)$ is a simple digraph,

$X, Y, Z \subseteq V$ and let f be a flow in N . We have

1. $f(X, X)=0$

2. $f(X, Y)=-f(Y, X)$

3. $f(X \cup Y, Z)=f(X, Z)+f(Y, Z)$ and

$f(Z, X \cup Y)=f(Z, X)+f(Z, Y)$ if $X \cap Y = \emptyset$

Ford-Fulkerson Method

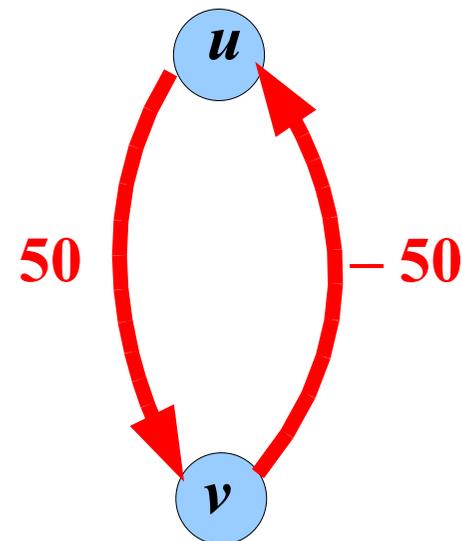
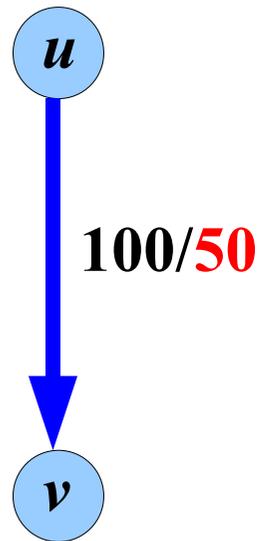
This method rests on the following three basic concepts: *residual network*, *augmenting path*, and *cut*.

It starts with a zero flow. By each iteration, an augmenting path is found from source s to target t along which an additional piece of flow can be added to augment the current flow. This process is repeated until no augmenting path can be found.

By establishing a relationship between a maximal flow and a minimal cut, it can be proved that the resulting augmented path is indeed maximal. The basic concepts will now be defined and explained.

Residual capacity

Define a flow f in a network $N=(G, s, t, c)$ where $G=(V, A)$ is a simple graph. For every pair of nodes $(u, v), u, v \in V$, define the *residual capacity* as $c_f(u, v) = c(u, v) - f(u, v)$.



Residual network

Let $N = (G, s, t, c)$ be a network with $G = (V, A)$ being a simple digraph.

Let f be a flow in N . Let c_f be the residual capacity of N defined by the flow f . Define a simple digraph $G_f(V, A_f)$ where

$A_f = \{(u, v) \mid u, v \in V \wedge c_f(u, v) > 0\}$. The network $N_f = (G_f, s, t, c_f)$ is called the ***residual network*** of network N with respect to flow f .

Lemma 2

Let $N = (G, s, t, c)$ be a network and f a flow in N . Let

$N_f = (G_f, s, t, c_f)$ be the residual network of N with respect to f and let

f^* be a flow in N_f . Then the mapping

$$(f + f^*): V \times V \rightarrow R$$

defined as

$$(f + f^*)(u, v) = f(u, v) + f^*(u, v)$$

is a flow in network N .

Augmenting path

Let $N = (G, s, t, c)$ be a network. Define a flow f in N and the residual capacity c_f with respect to this flow. Using c_f , a simple digraph

$G_f(V, A_f)$ may be built as above. Let now P be any path in G_f from source s to target t in. Such a path is called an **augmenting path** in N with respect to flow f . Let $P = (s = v_0, v_1, v_2, \dots, v_{k-1}, v_k = t)$. We define the **residual capacity** $c_f(P)$ of P with respect to f as follows:

$$c_f(P) = \min \{ c_f(v_i, v_{i+1}) \mid i = 0, 1, \dots, k-1 \}$$

Lemma 3

Let $N=(G, s, t, c)$ be a network, define a flow f in N and the residual network $N_f=(G_f, s, t, c_f)$. Let $P=(s=v_0, v_1, v_2, \dots, v_{k-1}, v_k=t)$ be an augmenting path in N_f and $c_f(P)$ its residual capacity with respect to f .

Define a mapping $f_P: V \times V \rightarrow R$ as follows:

1. $f_P(v_i, v_{i+1})=c_f(P), i=0,1,2, \dots, k-1$
2. $f_P(v_{i+1}, v_i)=-c_f(P), i=0,1,2, \dots, k-1$
3. $f_P(u, v)=0$ otherwise

Then f_P is a flow in G_f with $|f_P|=c_f(P)>0$

Corollary 4

Let $N = (G, s, t, c)$ be a network, f a flow defined in N ,

$N_f = (G_f, s, t, c_f)$ the residual network with respect to f , and P an augmenting path in G_f with $c_f(P)$ as its residual capacity. Let a mapping

$f_P: V \times V \rightarrow R$ be defined as in Lemma 3. Define a mapping

$f^* = f + f_P: V \times V \rightarrow R$ as in Lemma 2. Then f^* is a flow in N with

$$|f^*| = |f| + |f_P| > |f| .$$

Network cut and capacity

Let $N = (G, s, t, c)$ be a network with $G = (V, A)$ being a simple digraph.

We will call any partition (S, T) of V a **cut** of $N = (G, s, t, c)$ if $s \in S$ and $t \in T$. Recall that, for a partition (S, T) of V , we have $S \cup T = V$ and $S \cap T = \emptyset$.

Given a flow f in N , we define the **flow over cut** (S, T) with respect to f as $f(S, T)$ and the **capacity of cut** (S, T) as $c(S, T)$.

Note that, when computing the flow over a cut, the sum may include negative flows between nodes whereas the capacity of a cut is always composed of non-negative values.

Lemma 5

Let $N = (G, s, t, c)$ be a network, f a flow in N , and let (S, T) be a cut in N . Then the flow over the cut (S, T) with respect to f is equal to the value of the flow f , that is, $f(S, T) = |f|$.

Proof:

Since $S \cup T = V$ and $S \cap T = \emptyset$, we have $T = V - S$ and, using Lemma 1, we can write

$$\begin{aligned} f(S, T) &= f(S, V) - f(S, S) = f(S, V) = \\ &= f(s, V) + f(S - s, V) = f(s, V) = |f|. \end{aligned}$$

An immediate consequence of the above lemma is that the value of a flow is equal to the total flow into the target.

The next corollary shows how capacities can be used to establish an upper bound for a flow.

Corollary 6

The value of a flow in a network is less than the capacity of any cut of this network.

Proof: Let (S, T) be a cut. By Lemma 5 and by condition 1 in the definition of a flow, we have

$$|f| = f(S, T) = \sum_{u \in S} \sum_{v \in T} f(u, v) \leq \sum_{u \in S} \sum_{v \in T} c(u, v) = c(S, T) .$$

Theorem 7 (on maximal flow and minimal cut)

Let $N = (G, s, t, c)$ be a network and f a flow in N . Then the following conditions are equivalent:

- (a) f is a maximal flow in N
- (b) the residual network $N_f = (G_f, s, t, c)$ contains no augmenting paths
- (c) $|f| = c(S, T)$ for a cut (S, T) of N

Proof:

(a) \Rightarrow (b) Let f be a maximal flow in N and suppose that there is an augmenting path P in G_f . Then, by Corollary 4, $f^* = f + f_P: V \times V \rightarrow R$ is a flow in N such that $|f^*| > |f|$ which is a contradiction.

(b) \Rightarrow (c) : Let there be no augmenting paths in N so that no path exists in G_f from s to t . Define $S = \{u \in V \mid \text{there is a path in } G_f \text{ from } s \text{ to } u\}$, $T = V - S$. Now (S, T) is clearly a partition and a cut since, obviously, $s \in S$ and $t \notin S$ as no path exists in G_f from s to t .

For every $u \in S, v \in T$, we have $f(u, v) = c(u, v)$ since, otherwise, $(u, v) \in A_f$ and so $v \in S$. Therefore, by Lemma 5, $|f| = f(S, T) = c(S, T)$.

(c) \Rightarrow (a) : Let $|f| = c(S, T)$ for a cut (S, T) of N and suppose that f is not maximal. This means that there exists a flow f_1 such that $|f_1| > |f|$.

However, by Corollary 6, we have $|f_1| \leq c(S, T)$, which is a contradiction.

Ford-Fulkerson algorithm

For a network $N=(G, s, t, c)$ where $G=(V, A)$ is a simple digraph:

1. INITIALIZE: For every $u, v \in V$ put $f[u, v] := 0$

2. BUILD RESIDUAL NETWORK $N_f=(G_f, s, t, c_f)$: For every $u, v \in V$ calculate the residual capacity $c_f[u, v] := c[u, v] - f[u, v]$ to build the residual graph $G_f(V, A_f)$ with $A_f = \{(u, v) \mid u, v \in V \wedge c_f(u, v) > 0\}$

3. DETERMINE THE EXISTENCE OF A PATH IN G_f BETWEEN s AND t :

If no path exists: Stop. The current total flow f is maximal,

else create path $P=(s=v_0, v_1, a_2, v_2, \dots, v_{k-1}, a_k, v_k=t)$ and continue.

4. AUGMENT THE CURRENT FLOW

Calculate the residual capacity of P : $c_f(P) = \min\{c_f(v_i, v_{i+1}) \mid i=0, 1, \dots, k-1\}$

Put: $f[v_i, v_{i+1}] := f[v_i, v_{i+1}] + c_f(P)$, $f[v_{i+1}, v_i] := f[v_{i+1}, v_i] - c_f(P)$, $i=1, 2, \dots, k-1$

Go to Step 2.

