

```

using System;
using System.Collections.Generic;
using System.Linq;
using System.Text;
using System.Threading.Tasks;
using Microsoft.Research.Oslo;
using static System.Math;
using static System.Console;
using mat = MathNet.Numerics.LinearAlgebra.Matrix<double>;
using dmat = MathNet.Numerics.LinearAlgebra.Double.DenseMatrix;
using static MMP.Tools.GnuPlot;
using MMP.Tools;

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namespace Ballistics

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```

{
    class Program
    {
        static double scale = 1e-3;
        static double g = 9.80665 * scale;
        static double c = 0.03;

        static Vector fbal(double t, Vector x)
        {
            double y = x[0], v = x[1], a = x[2];
            //t = v[4];

            return new Vector(
                Tan(a),
                -(g * Sin(a) + c * v * v) / (v * Cos(a)),
                -g / (v * v)
                //v * Cos(a)
            );
        }
    }
}

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        );
    }

    static double Bisection(double v, double L, out List<IEnumerable<SolPoint>> sol, double a1 =
0.01, double a2 = PI / 4, double tol = 0.001, int maxit = 1000)
    {
        Vector y01 = new Vector(0, v, a1);
        Vector y02 = new Vector(0, v, a2);

        Options opt = new Options();
        opt.InitialStep = L / 100;
        double L1 = L + opt.InitialStep / 2;
        var ode1 = Ode.RK45(0, y01, fbal, opt);
        var ode2 = Ode.RK45(0, y02, fbal, opt);
        sol = new List<IEnumerable<SolPoint>>();
        sol.Add(ode1.SolveTo(L1));
        sol.Add(ode2.SolveTo(L1));

        double y1 = sol[0].Last().X[0];
        double y2 = sol[1].Last().X[0];

        if (y1 * y2 > 0)
        {
            WriteLine("No solution!");
            return double.NaN;
        }
        if (y1 == 0)
            return a1;
        if (y2 == 0)

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        return a2;

double dy = Abs(y2 - y1);
int it = 0;
double a = double.NaN;
IEnumerable<SolPoint> ode = null;
while (dy > tol && it < maxit)
{
    a = (a1 + a2) / 2;
    Vector y0 = new Vector(0, v, a);
    ode = Ode.RK45(0, y0, fbal, opt);
    double y = ode.SolveTo(L1).Last().X[0];
    if (y == 0)
        return a;
    if (y1 * y < 0)
    {
        y2 = y;
        a2 = a;
    }
    else
    {
        y1 = y;
        a1 = a;
    }
    it++;
    dy = Abs(y2 - y1);
}
sol.Add(ode.SolveTo(L1));
return a;
}

```

```

static void Main(string[] args)
{
    double v = 100 * scale;
    double L = 750 * scale;
    List<IEnumerable<SolPoint>> sol;
    double a = Bisection(v, L, out sol);
    WriteLine($"Cannon angle {a * 180 / PI}");

    mat data = new dmat(sol[2].Count(), 4);
    var e0 = sol[0].GetEnumerator();
    var e1 = sol[1].GetEnumerator();
    int i = 0;
    foreach (var item in sol[2])
    {
        data[i, 0] = item.T;
        data[i, 1] = item.X[0];
        e0.MoveNext();
        data[i, 2] = e0.Current.X[0];
        e1.MoveNext();
        data[i, 3] = e1.Current.X[0];
        i++;
    }
    var zeroline = dmat.OfArray(new double[,] { { 0, 0 }, { L, 0 } });
    FPlot(data, zeroline);
    WaitForKey();
}
}

public static void FPlot<T>(params Matrix<T>[] Y)

```

```

where T : struct, IEquatable<T>, IFormattable
{
    GnuPlot.Write2(Set);
    using (StreamWriter outputFile = new StreamWriter("data"))
    {
        for (int i = 0; i < Y.Length; i++)
        {
            DelimitedWriter.Write(outputFile, Y[i]);
            outputFile.WriteLine();
            outputFile.WriteLine();
            outputFile.WriteLine();
        }
    }

    foreach (var terminal in Terminals)
    {
        GnuPlot.WriteLine2(terminal.ToString());
        string s1, s2;
        for (int k = 0; k < Y.Length; k++)
        {
            for (int i = 1; i < Y[k].ColumnCount; i++)
            {
                if (k==0 && i == 1)
                    s1 = "plot ";
                else
                    s1 = "";
                if (k < Y.Length-1 || i < Y[k].ColumnCount - 1)
                    s2 = "@", "\";
                else
                    s2 = "";
            }
        }
    }
}

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        GnuPlot.WriteLine2("${s1}'data' i {k} u 1:{i + 1} w l t ''{s2}");  
    }  
}  
GnupStWr.Flush();  
}
```

