

stdafx.h

```
// stdafx.h : include file for standard system include files,  
// or project specific include files that are used frequently, but  
// are changed infrequently  
//
```

```
#pragma once  
#include "targetver.h"
```

```
// TODO: reference additional headers your program requires here
```

```
#include <iostream>  
#include <fstream>  
#include <vector>  
#include <valarray>  
#include <algorithm>  
#include <complex>  
#include <cmath>
```

```
using namespace std;  
using namespace std::complex_literals;
```

tools.h

```
#pragma once
```

```
#include "stdafx.h"
```

```

class Tools
{
public:
    template<typename T>
    static valarray<T> LinSpace(T a, T b, size_t n=100)
    {
        valarray<T> t(n+1);
        T dt = (b - a) / n;
        t[0] = a;
        for (size_t i = 1; i < n; i++)
            t[i] = t[i-1] + dt;
        t[n] = b;
        return t;
    }

private:
    Tools()
    {
    }
};

```

table.h

```
#pragma once
```

```
#include "stdafx.h"
```

```

template <typename T>
class Table
{
public:

```

```

Table(valarray<T> x)
{
    data.push_back(x);
}

Table(valarray<T> x, valarray<T> y)
{
    data.push_back(x);
    data.push_back(y);
    jagged = x.size() != y.size();
}

void Add(valarray<T> x)
{
    data.push_back(x);
    if (!jagged)
        jagged = x.size() != data[0].size();
}

void SetColumnwise(bool value)
{
    columnwise = value;
}

bool GetColumnwise()
{
    return columnwise;
}

void Print(ostream& out=cout)

```

```

{
    size_t length = data.size();
    if (columnwise)
        if (jagged)
            out << "Columns must have equal length!" << endl;
        else
            for (size_t irow = 0; irow < data[0].size(); irow++)
            {
                for (size_t icol = 0; icol < length; icol++)
                    out << data[icol][irow] << " ";
                out << endl;
            }
    else
        for (size_t icol = 0; icol < length; icol++)
        {
            for (size_t irow = 0; irow < data[icol].size(); irow++)
                out << data[icol][irow] << " ";
            out << endl;
        }
}

void Save(const char* filename)
{
    ofstream fout;
    fout.open(filename);
    Print(fout);
    fout.close();
    size_t length = data.size();
    fout.open("s.gpl");
    fout << "set yrange [-0.5:1.1]" << endl;
    fout << "plot ";

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        for (size_t i = 1; i < length; i++)
        {
            fout << " 'tab' u 1:" << i + 1 << " w 1";
            if (i == 1)
                fout << " t 'sin(x)/x'";
            else
                fout << " t 'T_{ " << i - 2 << " }'";
            if (i < length - 1)
                fout << ", \\";
            fout << endl;
        }
        fout << "set yrange restore" << endl;
        fout << "pause -1" << endl;
        fout.close();
    }

    ~Table()
    {
    }

private:
    vector<valarray<T>> data;
    bool columnwise = true;
    bool jagged = false;
};

```

Nm.cpp

```

// NM.cpp : Defines the entry point for the console application.
//

```

```

#include "stdafx.h"

```

```
#include "Tools.h"
#include "Table.h"

typedef double Real;
typedef complex<Real> Complex;

Real f(Real x)
{
    if (x != 0)
        return sin(x) / x;
    else
        return 1;
}

Complex cf(Complex z)
{
    return exp(z);
}

void real_computing(valarray<Real>& t)
{
    auto x = cos(t);
    auto y = sin(t);
    Table<Real> tab(x, y);
    tab.Print();
}

void complex_computing(valarray<Real>& t)
{
    valarray<Complex> u(t.size());
    for (size_t i = 0; i < t.size(); i++)
```

```

        u[i] = t[i] * 1i;
    auto z = u.apply(cf);
    Table<Complex> tab(u, z);
    tab.Print();
}

valarray<Real> Taylor(vector<Real> c, valarray<Real>& x)
{
    Real factorial = 1;
    for (size_t i = 2; i < c.size(); i++)
    {
        factorial *= i;
        c[i] /= factorial;
    }
    valarray<Real> T(x.size());
    for (int i = c.size() - 1; i > -1; i--) // Horner (Liu Hui 300 AC)
    {
        if (c[i] != 0)
            T += c[i];
        if (i > 0)
            T *= x;
    }
    return T;
}

int main()
{
    const Real PI = 3.141592653589793;
    size_t n = 300;
    auto t = Tools::LinSpace<Real>(0, 3*PI, n);

```

```
//real_computing(t);
//complex_computing(t);
Table<Real> tab(t, t.apply(f));

vector<Real> derivative;
Real s = 1;
for (size_t i = 0; i < 10; i++)
{
    derivative.push_back(s/(2*i+1));
    derivative.push_back(0);
    s = -s;
    auto T = Taylor(derivative, t);
    tab.Add(T);
}
tab.Save("tab");
return 0;
```

```
}
```

